

# Solving for Country Portfolios: Notes

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These notes refer to the two-country endowment model used as an example in Devereux and Sutherland (2006, 2007). The model equations are summarised below in their exact and approximated forms.

## Model Equations

- The budget constraint of home agents:

$$W_t = W_{t-1}r_{B^*,t} + Y_t - C_t + \alpha_{B,t-1}(r_{B,t} - r_{B^*,t}) \quad (1)$$

- Consumption Euler equations:

$$C_t^{-\rho} = \beta E_t [C_{t+1}^{-\rho} r_{B^*,t+1}] \quad C_t^{*-\rho} = \beta E_t [C_{t+1}^{*-\rho} r_{B^*,t+1}] \quad (2)$$

- Money demand:

$$M_t = P_t Y_t, \quad M_t^* = P_t^* Y_t^* \quad (3)$$

- Resource constraint:

$$C_t + C_t^* = Y_t + Y_t^* \quad (4)$$

- Return on bonds:

$$r_{B,t} = \frac{1}{Z_{t-1}P_t} \quad r_{B^*,t} = \frac{1}{Z_{t-1}^*P_t^*} \quad (5)$$

- Bond prices:

$$Z_t = \beta E_t [C_{t+1}^{-\rho} P_{t+1}^{-1}] C_t^\rho \quad Z_t^* = \beta E_t [C_{t+1}^{*-\rho} P_{t+1}^{*-1}] C_t^{*\rho} \quad (6)$$

- Endowments:

$$\log Y_t = \zeta_Y \log Y_{t-1} + \varepsilon_{Y,t} \quad \log Y_t^* = \zeta_Y \log Y_{t-1}^* + \varepsilon_{Y^*,t} \quad (7)$$

- Money supplies:

$$\log M_t = \zeta_M \log M_{t-1} + \varepsilon_{M,t} \quad \log M_t^* = \zeta_M \log M_{t-1}^* + \varepsilon_{M^*,t} \quad (8)$$

## Approximated model equations

- The budget constraint of home agents:

$$\begin{aligned}\hat{W}_t = & \frac{1}{\beta}\hat{W}_{t-1} + \hat{Y}_t - \hat{C}_t + \tilde{\alpha}\hat{r}_{x,t} + \\ & \frac{1}{2}\left[\hat{Y}_t^2 - \hat{C}_t^2 + \tilde{\alpha}(\hat{r}_{B,t}^2 - \hat{r}_{B^*,t}^2)\right] + \hat{\alpha}_{t-1}\hat{r}_{x,t} + \frac{1}{\beta}\hat{W}_{t-1}\hat{r}_{B^*,t}\end{aligned}\quad (9)$$

- Consumption Euler equations (combined):

$$\begin{aligned}-\rho\hat{C}_t + \rho\hat{C}_t^* = & E_t\left[-\rho\hat{C}_{t+1} + \rho\hat{C}_{t+1}^*\right] + \\ & \frac{1}{2}E_t\left[\rho^2\hat{C}_{t+1}^2 + \hat{r}_{B^*,t+1}^2 - 2\rho\hat{C}_{t+1}\hat{r}_{B^*,t+1}\right] - \frac{1}{2}\rho^2\hat{C}_t^2 - \\ & \frac{1}{2}E_t\left[\rho^2\hat{C}_{t+1}^{*2} + \hat{r}_{B^*,t+1}^2 - 2\rho\hat{C}_{t+1}^*\hat{r}_{B^*,t+1}\right] + \frac{1}{2}\rho^2\hat{C}_t^{*2}\end{aligned}\quad (10)$$

- Money demand:

$$\hat{M}_t = \hat{P}_t + \hat{Y}_t \quad \hat{M}_t^* = \hat{P}_t^* + \hat{Y}_t^* \quad (11)$$

- Resource constraint:

$$\hat{C}_t + \hat{C}_t^* = \hat{Y}_t + \hat{Y}_t^* + \frac{1}{2}(\hat{C}_t^2 + \hat{C}_t^{*2} - \hat{Y}_t^2 - \hat{Y}_t^{*2}) \quad (12)$$

- Return on bonds:

$$\hat{r}_{B,t} = -\hat{Z}_{t-1}^d - \hat{P}_t \quad \hat{r}_{B^*,t} = -\hat{Z}_{t-1}^{d*} - \hat{P}_t^* \quad (13)$$

- Bond prices:

$$\begin{aligned}\hat{Z}_t = & E_t\left[-\rho\hat{C}_{t+1} - \hat{P}_{t+1}\right] + \rho\hat{C}_t + \\ & \frac{1}{2}E_t\left[\rho^2\hat{C}_{t+1}^2 + \hat{P}_{t+1}^2 - 2\rho\hat{C}_{t+1}\hat{P}_{t+1}\right] - \frac{1}{2}\left[\rho^2\hat{C}_t^2 + \hat{Z}_t^2 - 2\rho\hat{C}_t\hat{Z}_t\right]\end{aligned}\quad (14)$$

$$\begin{aligned}\hat{Z}_t^* = & E_t\left[-\rho\hat{C}_{t+1} - \hat{P}_{t+1}^*\right] + \rho\hat{C}_t^* + \\ & \frac{1}{2}E_t\left[\rho^2\hat{C}_{t+1}^2 + \hat{P}_{t+1}^{*2} - 2\rho\hat{C}_{t+1}\hat{P}_{t+1}^*\right] - \frac{1}{2}\left[\rho^2\hat{C}_t^2 + \hat{Z}_t^{*2} - 2\rho\hat{C}_t^*\hat{Z}_t^*\right]\end{aligned}\quad (15)$$

- Excess return and consumption difference:

$$\hat{r}_{x,t} = \hat{r}_{B,t} - \hat{r}_{B^*,t} \quad \hat{C}_t^D = \hat{C}_t - \hat{C}_t^* \quad (16)$$

- Dummy variables:

$$\hat{Z}_t^d = \hat{Z}_t \quad \hat{Z}_t^{d*} = \hat{Z}_t^* \quad (17)$$

- Endowments:

$$\hat{Y}_t = \zeta_Y\hat{Y}_{t-1} + \varepsilon_{Y,t} \quad \hat{Y}_t^* = \zeta_Y\hat{Y}_{t-1}^* + \varepsilon_{Y^*,t} \quad (18)$$

- Money supplies:

$$\hat{M}_t = \zeta_M\hat{M}_{t-1} + \varepsilon_{M,t} \quad \hat{M}_t^* = \zeta_M\hat{M}_{t-1}^* + \varepsilon_{M^*,t} \quad (19)$$

## Zero-order portfolio

Devereux and Sutherland (2006) show that the solution for the zero-order component of portfolios,  $\tilde{\alpha}$ , can be derived using a first-order approximation of the model. This can be written in the form

$$A_1 \begin{bmatrix} s_{t+1} \\ E_t[c_{t+1}] \end{bmatrix} = A_2 \begin{bmatrix} s_t \\ c_t \end{bmatrix} + A_3 x_t + B \xi_t + O(\epsilon^2) \quad (20)$$

$$x_t = N x_{t-1} + \varepsilon_t \quad (21)$$

where the vectors  $s$ ,  $c$  and  $x$  are defined as

$$s_t = \begin{bmatrix} \hat{W}_{t-1} & \hat{Z}_{t-1}^d & \hat{Z}_{t-1}^{d*} \end{bmatrix}' \quad (22)$$

$$c_t = \begin{bmatrix} \hat{C}_t & \hat{C}_t^* & \hat{P}_t & \hat{P}_t^* & \hat{r}_{B,t} & \hat{r}_{B^*,t} & \hat{Z}_t & \hat{Z}_t^* & \hat{r}_{x,t} & \hat{C}_t^D \end{bmatrix}' \quad (23)$$

$$x_t = \begin{bmatrix} \hat{Y}_t & \hat{Y}_t^* & \hat{M}_t & \hat{M}_t^* \end{bmatrix}' \quad (24)$$

and the coefficient matrices are constructed from the first-order parts of equations (9) to (17). The term  $\tilde{\alpha} \hat{r}_{x,t}$  in the budget constraint is replaced with  $\xi_t$ . The solution to this system can be written in the form:

$$s_{t+1} = F_1 x_t + F_2 s_t + F_3 \xi_t + O(\epsilon^2) \quad (25)$$

$$c_t = P_1 x_t + P_2 s_t + P_3 \xi_t + O(\epsilon^2) \quad (26)$$

The solution procedure for  $\tilde{\alpha}$  requires expressions for  $\hat{r}_{x,t+1}$  and  $\hat{C}_{t+1}^D$  of the following form

$$\hat{r}_{x,t+1} = R_1 \xi_{t+1} + R_2 \varepsilon_{t+1} + O(\epsilon^2) \quad (27)$$

$$\hat{C}_{t+1}^D = D_1 \xi_{t+1} + D_2 \varepsilon_{t+1} + D_3 z_t + O(\epsilon^2) \quad (28)$$

where  $z_t = \begin{bmatrix} x_t & s_{t+1} \end{bmatrix}'$ . These expressions can be obtained by combining (21) and (26) to yield

$$c_{t+1} = Q_1 \xi_{t+1} + Q_2 \varepsilon_{t+1} + Q_3 z_t + O(\epsilon^2) \quad (29)$$

where

$$Q_1 = P_3 \quad Q_2 = P_1 \quad Q_3 = [P_1 N, P_2] \quad (30)$$

$\hat{r}_{x,t+1}$  is the ninth element of  $c_{t+1}$ , so  $R_1$  and  $R_2$  are the ninth rows of  $Q_1$  and  $Q_2$  respectively. Likewise,  $\hat{C}_{t+1}^D$  is the tenth element of  $c_{t+1}$ , so  $D_1$ ,  $D_2$  and  $D_3$  are the tenth rows of  $Q_1$ ,  $Q_2$  and  $Q_3$  respectively.

## First-order portfolio

Devereux and Sutherland (2007) show that the solution for the first-order component of portfolios,  $\hat{\alpha}$ , can be derived using a second-order approximation of the model. This can be written in the form

$$\tilde{A}_1 \begin{bmatrix} s_{t+1} \\ E_t[c_{t+1}] \end{bmatrix} = \tilde{A}_2 \begin{bmatrix} s_t \\ c_t \end{bmatrix} + \tilde{A}_3 x_t + \tilde{A}_4 \Lambda_t + \tilde{A}_5 E_t[\Lambda_{t+1}] + B\xi_t + O(\epsilon^3) \quad (31)$$

$$x_t = Nx_{t-1} + \varepsilon_t \quad (32)$$

$$\Lambda_t = \text{vech} \left( \begin{bmatrix} x_t \\ s_t \\ c_t \end{bmatrix} \begin{bmatrix} x_t & s_t & c_t \end{bmatrix} \right) \quad (33)$$

where again the vectors  $s$ ,  $c$  and  $x$  are defined as above and the coefficient matrices are constructed from equations (9) to (17). The term  $\hat{\alpha}_{t-1}\hat{r}_{x,t}$  in the budget constraint is replaced with  $\xi_t$  and  $\tilde{\alpha}$  is set at the value derived using the first-order approximation of the model. The solution to this system can be written in the form:

$$s_{t+1} = \tilde{F}_1 x_t + \tilde{F}_2 s_t + \tilde{F}_3 \xi_t + \tilde{F}_4 V_t + \tilde{F}_5 \Sigma + O(\epsilon^3) \quad (34)$$

$$c_t = \tilde{P}_1 x_t + \tilde{P}_2 s_t + \tilde{P}_3 \xi_t + \tilde{P}_4 V_t + \tilde{P}_5 \Sigma + O(\epsilon^3) \quad (35)$$

The solution procedure for  $\hat{\alpha}$  requires expressions for  $\hat{r}_{x,t+1}$  and  $\hat{C}_{t+1}^D$  of the following form

$$\begin{aligned} \hat{r}_x &= [\tilde{R}_0] + [\tilde{R}_1]\xi + [\tilde{R}_2]_i[\varepsilon]^i + [\tilde{R}_3]_k([z^f]^k + [z^s]^k) \\ &\quad + [\tilde{R}_4]_{i,j}[\varepsilon]^i[\varepsilon]^j + [\tilde{R}_5]_{k,i}[\varepsilon]^i[z^f]^k + [\tilde{R}_6]_{i,j}[z^f]^i[z^f]^j + O(\epsilon^3) \end{aligned} \quad (36)$$

$$\begin{aligned} \hat{C}_{t+1}^D &= [\tilde{D}_0] + [\tilde{D}_1]\xi + [\tilde{D}_2]_i[\varepsilon]^i + [\tilde{D}_3]_k([z^f]^k + [z^s]^k) \\ &\quad + [\tilde{D}_4]_{i,j}[\varepsilon]^i[\varepsilon]^j + [\tilde{D}_5]_{k,i}[\varepsilon]^i[z^f]^k + [\tilde{D}_6]_{i,j}[z^f]^i[z^f]^j + O(\epsilon^3) \end{aligned} \quad (37)$$

The appendix to Devereux and Sutherland (2007) shows that these expressions can be obtained by rewriting (35) as follows

$$\begin{aligned} c &= \tilde{Q}_0 + \tilde{Q}_1 \xi + \tilde{Q}_2 \varepsilon + \tilde{Q}_3 (z^f + z^s) + \\ &\quad \tilde{Q}_4 \text{vech}(\varepsilon \varepsilon') + \tilde{Q}_5 \text{vec}(\varepsilon z^{f'}) + \tilde{Q}_6 \text{vech}(z^f z^{f'}) + O(\epsilon^3) \end{aligned} \quad (38)$$

where time subscripts have been omitted and

$$\tilde{Q}_0 = \tilde{P}_5 \text{vech}(\Sigma) \quad \tilde{Q}_1 = \tilde{P}_3 \quad \tilde{Q}_3 = [\tilde{P}_1 N, \tilde{P}_2] \quad \tilde{Q}_4 = \tilde{P}_4 X_1 \quad \tilde{Q}_5 = \tilde{P}_4 X_2 \quad \tilde{Q}_6 = \tilde{P}_4 X_3 \quad (39)$$

$$X_1 = L^c U_2 \otimes U_2 L^h \quad X_2 = L^c \left[ U_2 \otimes U_1 + U_1 \otimes U_2 P' \right] \quad X_3 = L^c U_1 \otimes U_1 L^h$$

$$U_1 = \begin{bmatrix} N & 0 \\ 0 & I \end{bmatrix}, \quad U_2 = \begin{bmatrix} I \\ 0 \end{bmatrix}$$

The matrices  $L^c$  and  $L^h$  are conversion matrices such that

$$\text{vech}(\cdot) = L^c \text{vec}(\cdot), \quad L^h \text{vech}(\cdot) = \text{vec}(\cdot)$$

and  $P$  is a ‘permutation matrix’ such that, for any matrix  $Z$ ,

$$\text{vec}(Z) = P \text{vec}(Z')$$

$\hat{r}_x$  is the ninth element of  $c$ , so  $\tilde{R}_1, \tilde{R}_2, \tilde{R}_3, \tilde{R}_4, \tilde{R}_5$  and  $\tilde{R}_6$  are formed from the ninth rows of  $\tilde{Q}_1, \tilde{Q}_2, \tilde{Q}_3, \tilde{Q}_4, \tilde{Q}_5$  and  $\tilde{Q}_6$  respectively.  $\hat{C}_{t+1}^D$  is the tenth element of  $c$ , so  $\tilde{D}_1, \tilde{D}_2, \tilde{D}_3, \tilde{D}_4, \tilde{D}_5$  and  $\tilde{D}_6$  are formed from the tenth rows of  $\tilde{Q}_1, \tilde{Q}_2, \tilde{Q}_3, \tilde{Q}_4, \tilde{Q}_5$  and  $\tilde{Q}_6$  respectively.

## References

- [1] Devereux, M and A Sutherland (2006) “Solving for Country Portfolios in Open Economy Macro Models” CEPR Discussion Paper No 5966.
- [2] Devereux, M and A Sutherland (2007) “Country Portfolio Dynamics” CEPR Discussion Paper No 6208.
- [3] Lombardo, G and A. Sutherland (2007) “Computing Second-Order-Accurate Solutions for Rational Expectation Models using Linear Solution Methods” *Journal of Economic Dynamics and Control*, 31, 515-530.